9	И	44	ω	N	4	
436	1372	12924	60684	393910	19121	Hits
S1 and S2 and S3 and S4 and S5	S4 same ((writ\$4 record\$6) near4 (correct\$4 compensat\$4 bcv\$1 rcv\$1 offset\$1 (off adj set\$1) microjog\$4 (micro adj jog\$4) RPE\$1 (repeat\$4 adj2 error\$1) RRO\$1 WRO\$1 WRRO\$1 CRRO\$1 WIRRO\$1 misregist\$7 TMR\$1 WTMR\$1 WTMR\$1 OTRC OTC ZAP (zero adj acceleration adj path\$1) (virtual adj (circle circular) adj orbit\$1))	(servowrit\$4 servotrackwrit\$4 selfservowrit\$4 STW\$1 SSW\$1 ((record\$6 writ\$4) near4 (servo\$11 positioning burst\$1 pattern\$1))) near8 (final\$2 last\$2 second\$2 permanent\$2 user product\$4 fixed ultimate\$2 actual\$2 result\$5 full real correct\$2)	((position\$3 control\$4 guid\$4 tracking center\$3 following servoposition\$3 servocontrol\$4) near5 (head\$1 actuator arm\$1 vcm HGA HSA)) same (correct\$4 compensat\$4 bcv\$1 rcv\$1 offset\$1 (off adj set\$1) microjog\$4 (micro adj jog\$4) RPE\$1 (repeat\$4 adj2 error\$1) RRO\$1 WRO\$1 WRRO\$1 CRRO\$1 WIRRO\$1 misregist\$7 TMR\$1 WTMR\$1 OTRC OTC ZAP (zero adj acceleration adj path\$1) (virtual adj (circle circular) adj orbit\$1))	(servotrackwrit\$4 selfservowrit\$4 STW\$1 SSW\$1 record\$6 writ\$4 servo\$11 positioning burst\$1 pattern\$1 initial\$2 first temporar\$3 bas\$2 tim\$3 reference propagation origin\$4) same ((position\$3 control\$4 guid\$4 tracking center\$3 following servoposition\$3 servocontrol\$4) near5 (head\$1 actuator arm\$1 vcm HGA HSA))	(servowrit\$4 servotrackwrit\$4 selfservowrit\$4 STW\$1 SSW\$1 ((record\$6 writ\$4) near4 (servo\$11 positioning burst\$1 pattern\$1))) near8 (initial\$2 first temporar\$3 bas\$2 tim\$3 reference propagation origin\$4)	Search Text
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